

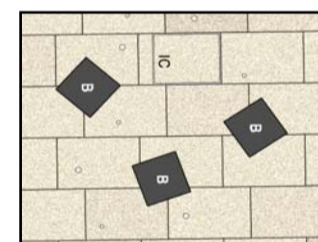
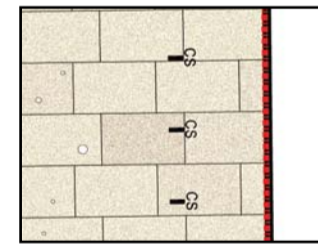
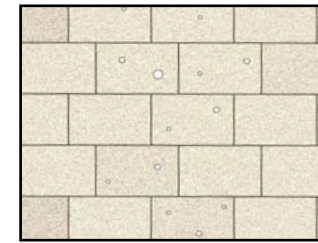
Carlos Place

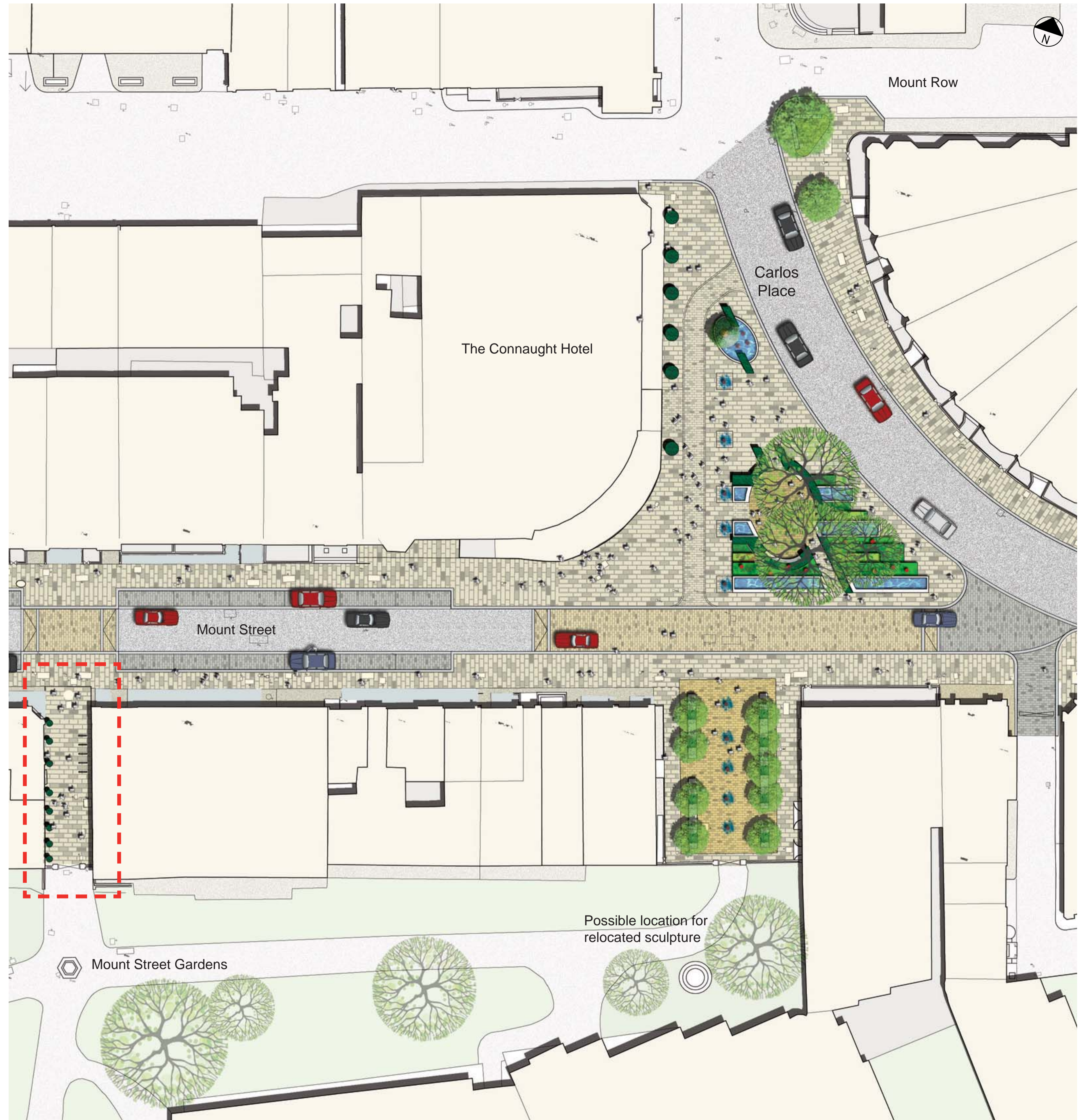
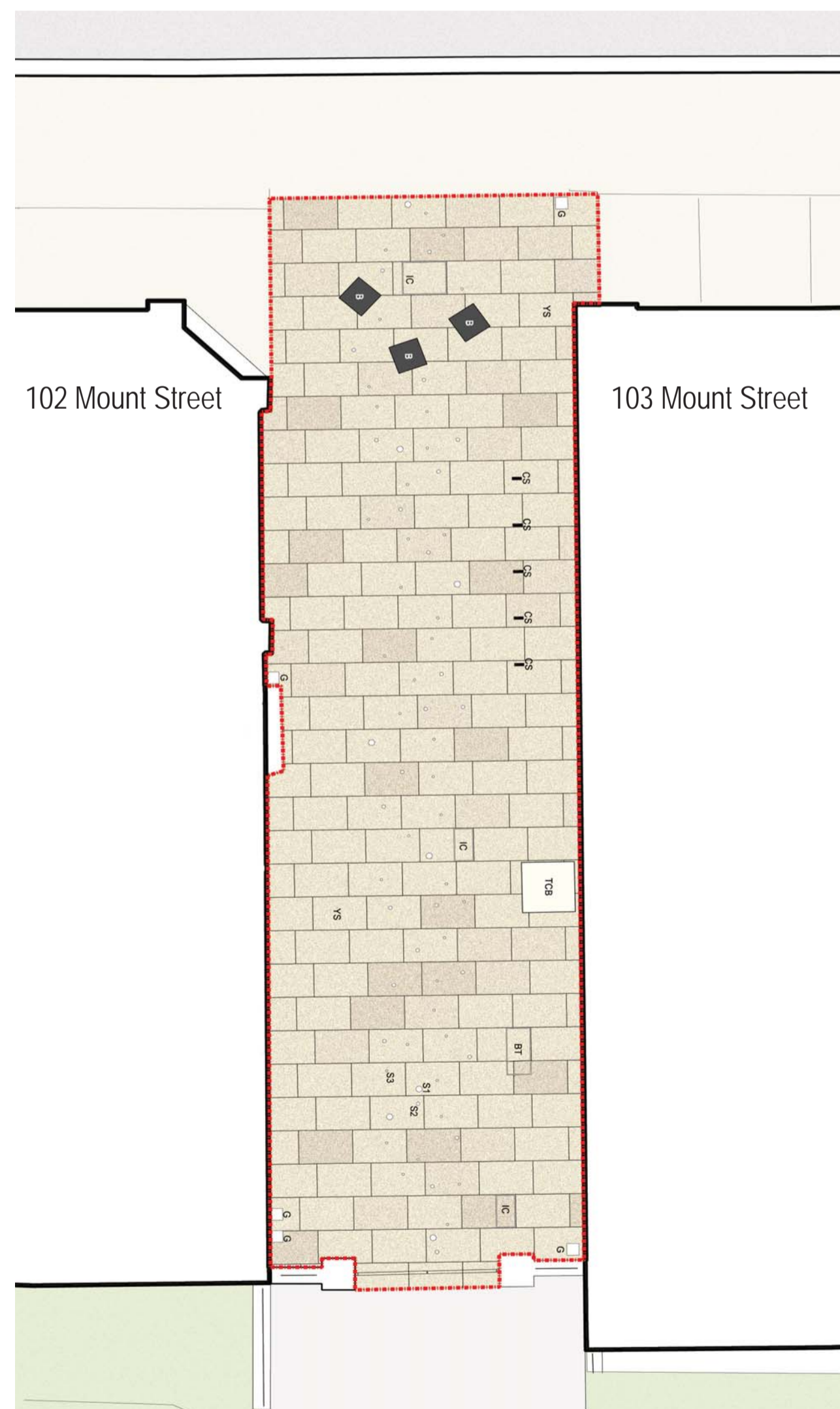
- To create an outstanding space at Carlos Place which acts as a unifying element for Mount Street between South Audley Street and Davies Street.
- To create a key space, accessible to pedestrians, including high quality materials, water features and lighting, provision for a Christmas tree, and a semi-enclosed pocket garden in the heart of Carlos Place and Mount Street.
- To enhance the relationship of Carlos Place to the Connaught Hotel and street through the removal of carriageway and the introduction of 'shared surfacing', with a drop-off and pick up facility.
- To introduce enhanced surfacing materials within Carlos Place, Mount Street and the entrance to Mount Street Gardens.
- The retention and enhancement of mature trees, introduction of planting, water and a place to sit within Carlos Place and Mount Street.
- The improvement of visual and physical connections between Carlos Place and Mount Street Gardens.
- The provision of clear lines of sight from the Connaught Hotel to the taxi rank in Mount Row.
- The creation of a threshold space with new trees and planting at the entrance to Mount Street Gardens.
- The introduction of innovative lighting and public art that complements and enhances the design.
- The relocation of the existing sculpture in Carlos Place, possibly to Mount Street Gardens at the termination of an axis of water features.

The Mount Street Pilot Project

The entrance passage to Mount Street Gardens between 102 and 103 Mount Street is an opportunity to pilot the high quality materials and workmanship proposed along the rest of Mount Street. As a permanent piece of improvement works, this will be constructed and completed before the end of 2008.

Materials Key

-  Seats:
Black granite cubes
-  Cycle Stands:
Illustrated on Proposed Materials board.
-  Bronze Plaques set into
yorkstone pavement
linking Mount Street to
Mount Street Gardens



Refer to the key on the Landscape Masterplan